MATH 590: QUIZ 5 SOLUTIONS

Name:

1. Let $T: V \to W$ be a linear transformation of vectors spaces with scalars in F. Define: (a) The *kernel* of T and (b) The *image* of T. (2 points)

Solution. The kernel of T is the set of vectors $v \in V$ such that $T(v) = \vec{0}$ and the image of T is the set of vectors $w \in W$ that can be written as w = T(v), for some $v \in V$.

2. Let $T : \mathbb{R}^2 \to \mathbb{R}^2$ be defined by T(x, y) = (y, x) and $S : \mathbb{R}^2 \to \mathbb{R}^2$ be defined by S(x, y) = (x + 7, x - y). Let $\alpha := \{(-1, 1), (0, 1)\}, \beta := \{(1, 0), (1, 1)\}, \text{ and } \gamma := \{(0, -1), (-2, 0)\}$ be bases for \mathbb{R}^2 . Verify that $[ST]^{\alpha}_{\alpha} = [S]^{\gamma}_{\beta} \cdot [T]^{\beta}_{\alpha}$. (4 points)

Solution. We have ST(-1,1) = S(1,-1) = (8,2) = -2(0,-1) + -4(-2,0) and ST(0,1) = S(1,0) = (8,1) = -1(0,-1) + -4(-2,0). Thus, $[ST]^{\gamma}_{\alpha} = \begin{pmatrix} -2 & -1 \\ -4 & -4 \end{pmatrix}$. On the other hand, T(-1,1) = (1,-1) = 2(1,0) + -1(1,1) and T(0,1) = (1,0) = 1(1,0) + 0(1,1). Thus, $[T]^{\beta}_{\alpha} = \begin{pmatrix} 2 & 1 \\ -1 & 0 \end{pmatrix}$. S(1,0) = (8,1) = -1(0,-1) + -4(-2,0) and S(1,1) = (8,0) = 0(0,-1) + -4(-2,0). Thus, $[S]^{\gamma}_{\beta} = \begin{pmatrix} -1 & 0 \\ -4 & -4 \end{pmatrix}$. Therefore

$$[S]^{\gamma}_{\beta} \cdot [T]^{\beta}_{\alpha} = \begin{pmatrix} -1 & 0\\ -4 & -4 \end{pmatrix} \cdot \begin{pmatrix} 2 & 1\\ -1 & 0 \end{pmatrix} = \begin{pmatrix} -2 & -1\\ -4 & -4 \end{pmatrix} = [ST]^{\gamma}_{\alpha}.$$

3. $A = \begin{pmatrix} a & d & g \\ b & e & h \\ c & f & i \end{pmatrix}$, and write C_1, C_2, C_3 for the columns of A. Verify that $A \cdot \begin{pmatrix} u \\ v \\ w \end{pmatrix} = uC_1 + vC_2 + wC_3$. (4 points)

Solution. On the one hand, $A \cdot \begin{pmatrix} u \\ v \\ w \end{pmatrix} = \begin{pmatrix} a & d & g \\ b & e & h \\ c & f & i \end{pmatrix} \cdot \begin{pmatrix} u \\ v \\ w \end{pmatrix} = \begin{pmatrix} ua + vd + wg \\ ub + ve + wh \\ uc + vf + wi \end{pmatrix}$. While on the other hand, $uC_1 + vC_2 + wC_3 = u \begin{pmatrix} a \\ b \\ c \end{pmatrix} + v \begin{pmatrix} d \\ e \\ f \end{pmatrix} + w \begin{pmatrix} g \\ h \\ i \end{pmatrix} = \begin{pmatrix} ua + vd + wg \\ ub + ve + wh \\ uc + vf + wi \end{pmatrix}$ which gives what we want

which gives what we want.